

OCCUPANCY MODELING OF BIRDS IN THE AMAZON RAINFOREST

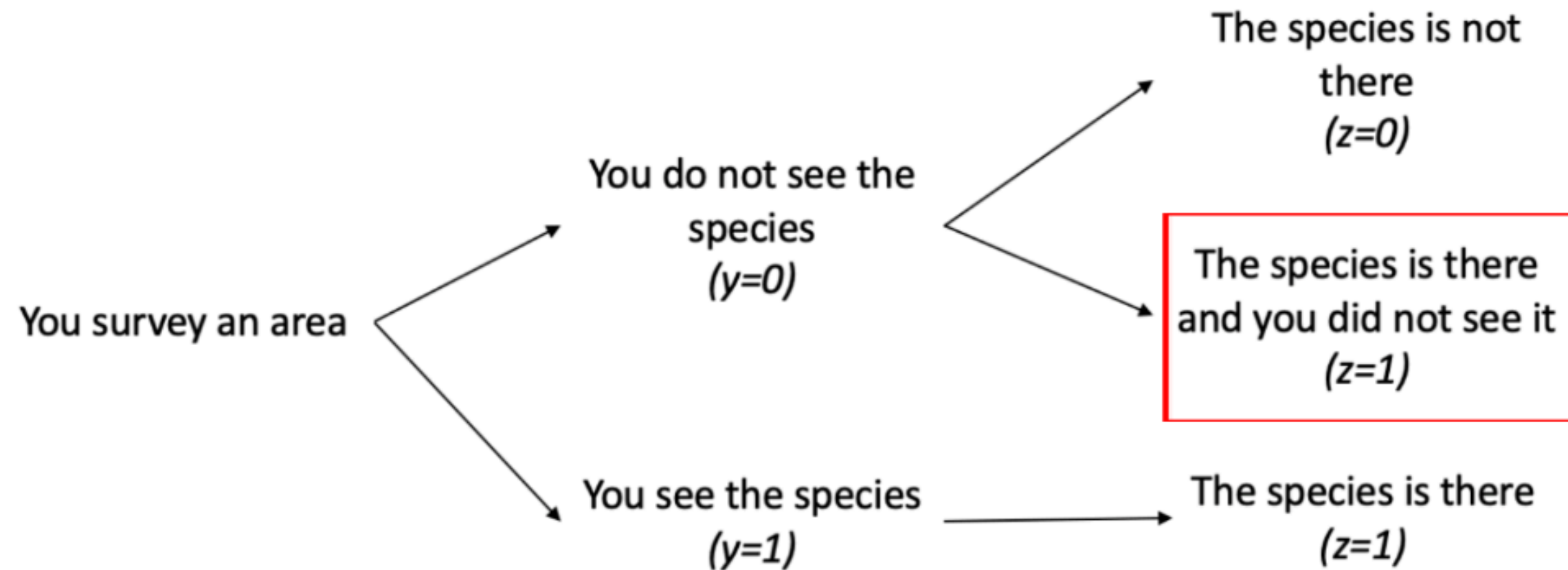
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BACKGROUND



**OCCUPANCY
MODELS TRY TO
ACCOMMODATE
IMPERFECT
DETECTION**



Observational flow chart relevant for occupancy modeling. The red box contains the possibility of imperfect detection. Variables y and z correspond to detection and occupancy, respectively. Taken from [kevintshoemaker.github.io](https://github.com/kevintshoemaker), produced by Morgan Byrne, James Golden.

PROJECT GOALS



Has climate change or forest loss affected bird populations in the Amazonas region of Brazil over the last 12 years?



Tested this for two species:

Generalist species: Black vulture (*Coragyps atratus*)

Forest specialist: Screaming piha (*Lipaugus vociferans*)



Test performance of various occupancy models

DATA COLLECTION



EBird Data:

2012–2021

<https://ebird.org/home>

Climate Data (Worldclim):

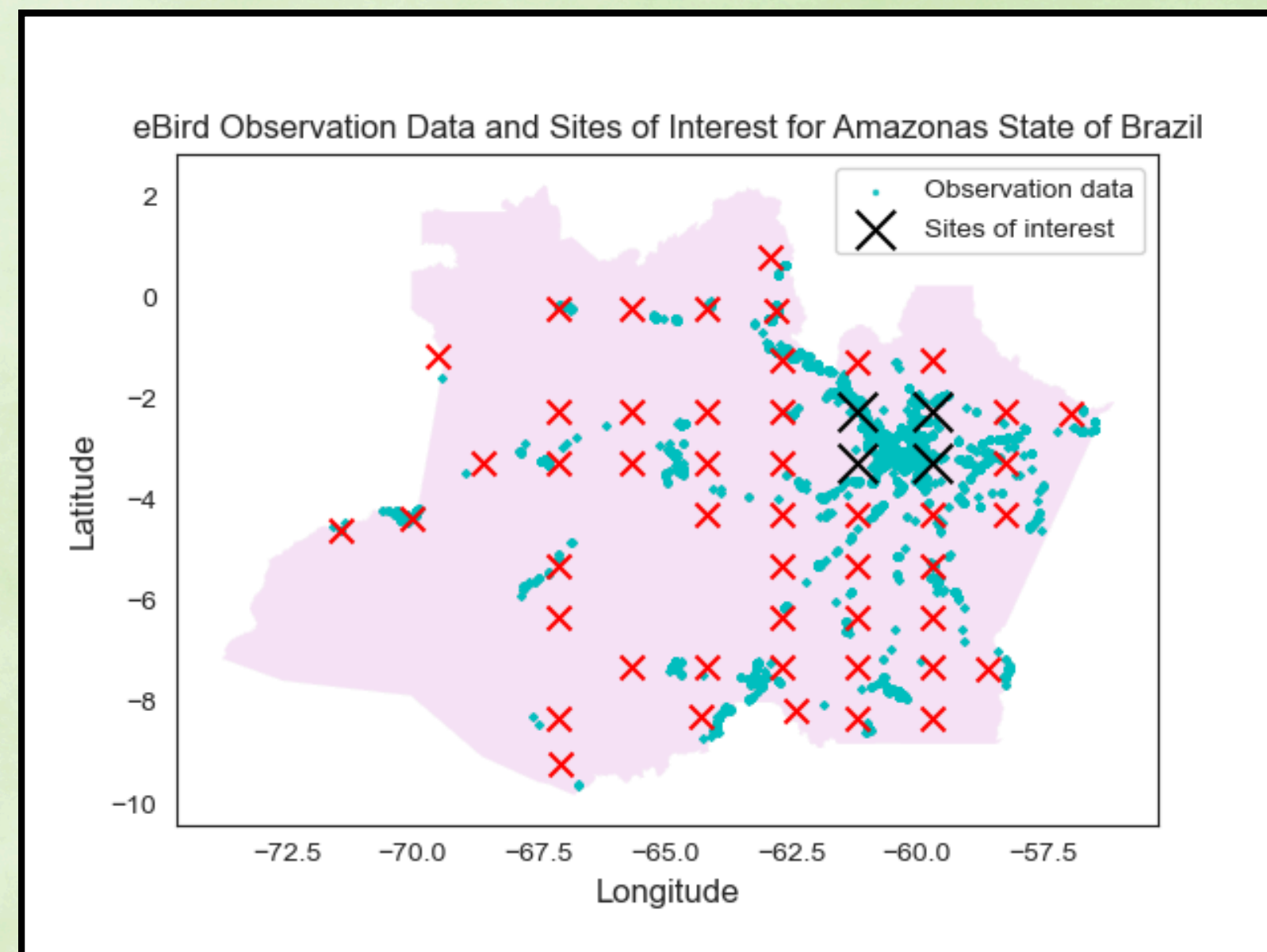
Temperature and precipitation

<https://www.worldclim.org/data/worldclim21.html>

Tree cover and tree cover loss Data:

Enhanced Vegetation Index (EVI), Tree cover loss, Tree cover loss by fires

<https://lpdaac.usgs.gov/products/mod13q1v061/>; <https://www.globalforestwatch.org/dashboards/country/BRA/>



DATA COLLECTION



- Occupancy covariates: Precipitation, Temperature, EVI, Tree Cover Loss, Tree Cover Loss by Fires
- Detection covariates: Year, Day of Year, Time of Day, Number of Observers, Effort Hours, Effort distance

ML PREPROCESSING



Interested in the effects of environmental covariates over time.

But still want to model occupancy as with supervised learning (classification) techniques.

Solution: Create new features shifted by a time step

| Target | Time Step | Feature (t) | Feature (t-1) |
|--------|-----------|-------------|---------------|
| y4 | 4 | | |
| y3 | 3 | | |
| y2 | 2 | | |
| y1 | 1 | | |
| y0 | 0 | | |

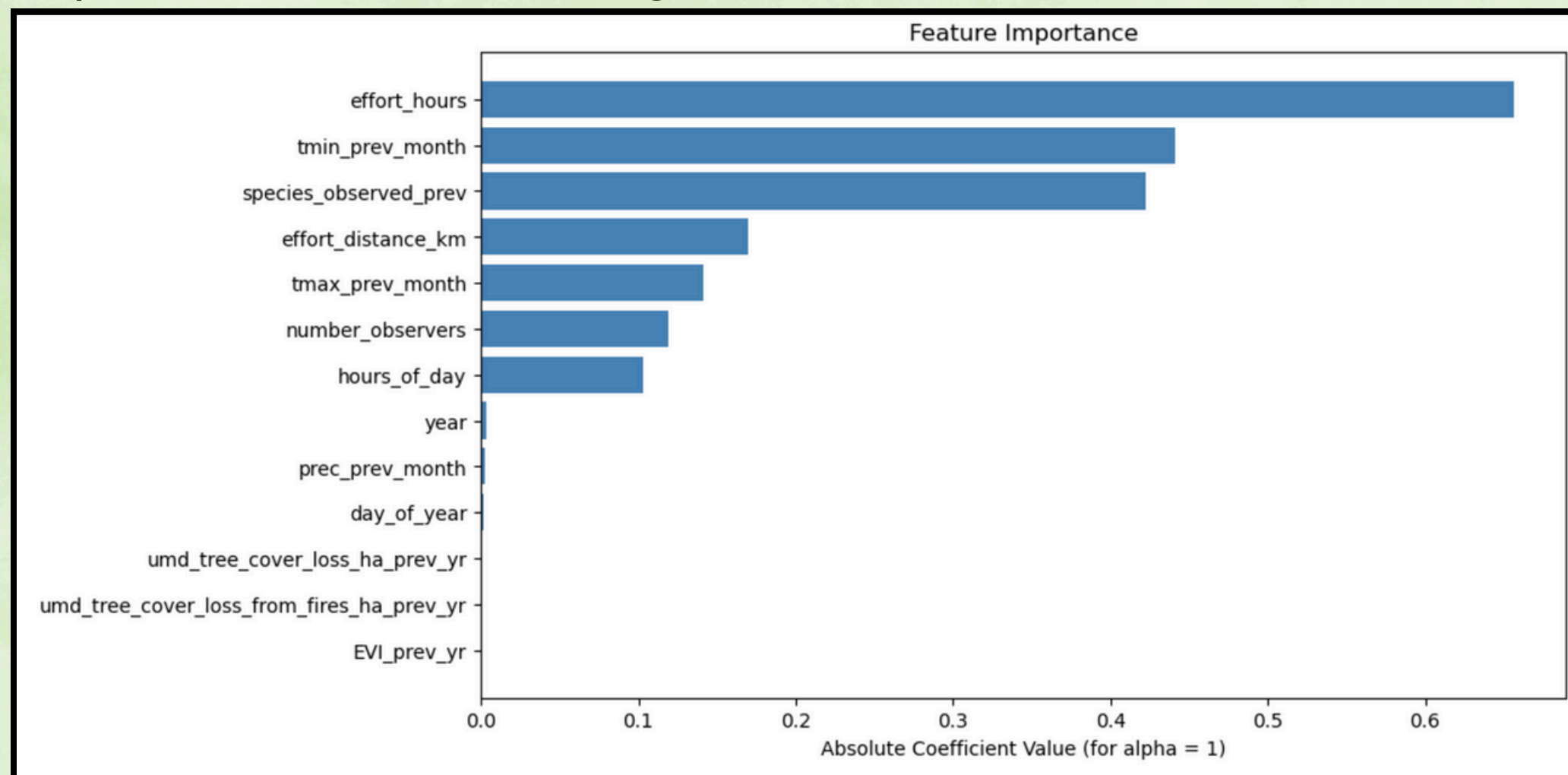
Use value of Feature at Time Step t-1 to predict Target at Time Step t

Our shifted features:
EVI, tree cover loss, precipitation, temperature, and previous occupancy

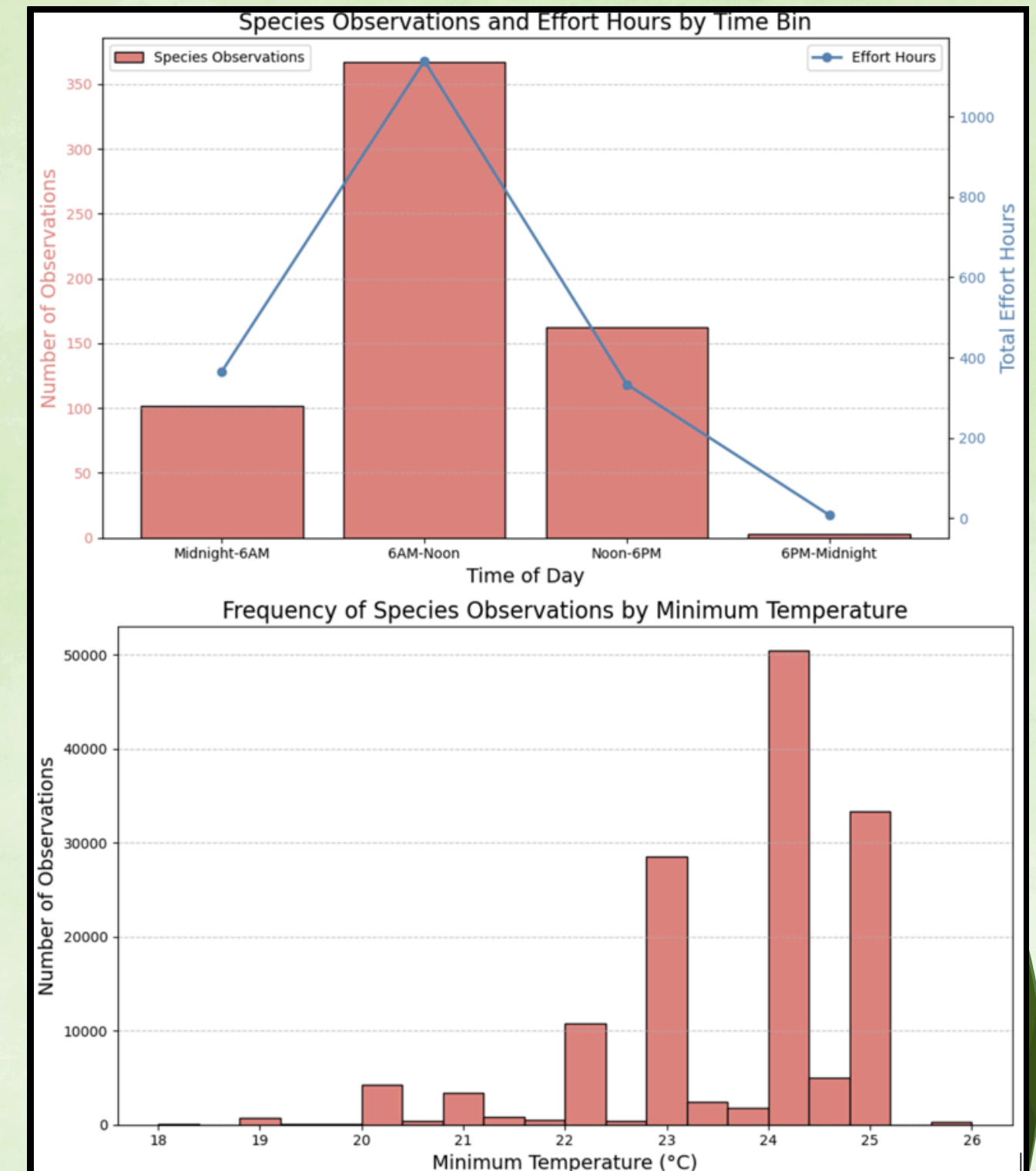
ML MODELING APPROACH 1

1. BINARY LOGISTIC REGRESSION

Implemented with L1 regularization for feature selection



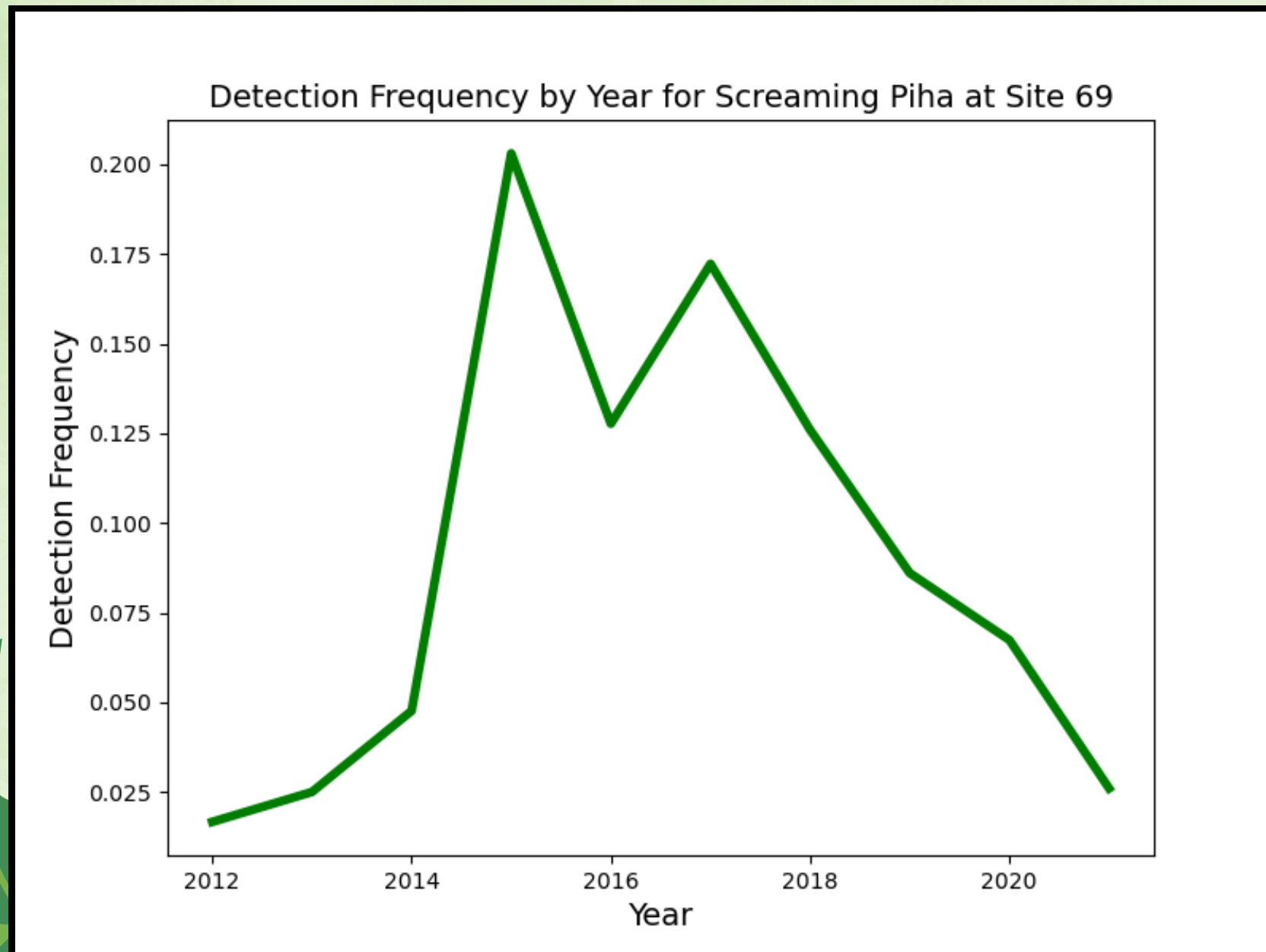
1. Effort hours (Detection covariates)
2. Minimum temperature (Occupancy covariates)
3. Species previously observed



ML MODELING APPROACH 2



2. (BALANCED) RANDOM FOREST

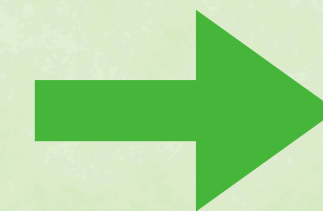
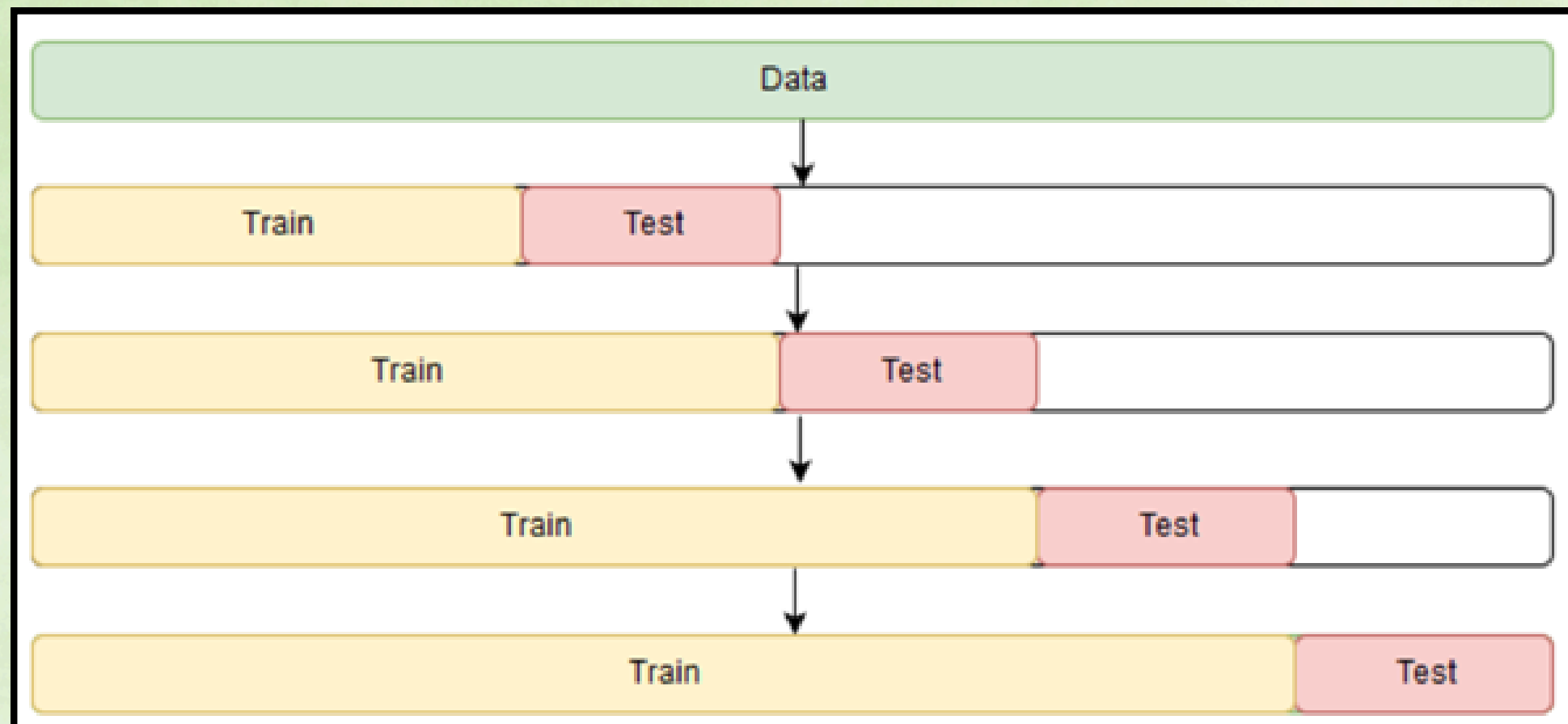


eBird data tends to suffer from class imbalance
To accommodate this, we implement a balanced random forest - like a traditional random forest but draws a bootstrap sample from the minority class and samples the same number from the majority class.

BEST ML MODEL



Also try augmenting our ML approaches with Synthetic Minority Over-Sampling Technique (SMOTE) - generate synthetic data for minority class to help with class imbalance



Compare our ML models with rolling cross-validation

Best ML classification model - Binary logistic regression with L1 regularization and SMOTE (based on F1 score)

Image from: 'Cross Validation in Time Series,' Soumya Shrivastava, *Medium*

MODELING APPROACH



3. SPOCCUPANCY MODELS IN RSTUDIO

We use spOccupancy library in R to fit a spatial occupancy model.

This will allow us to accommodate imperfect detection.

Our occupancy covariates are temperature, precipitation, tree cover loss, EVI

While our detection covariates are day-of-the-year, time-of-day, effort, and number of observation

BASIC MODEL STATEMENT

$$y_i | z_i \sim \text{Bernoulli}(p \cdot z)$$

$$z_i \sim \text{Bernoulli}(\psi)$$

$$\text{logit}(p) = \alpha_0 + \sum_j \alpha_j \cdot A_j$$

$$\text{logit}(\psi) = \beta_0 + \sum_j \beta_j \cdot B_j$$

with

y_i = data at site i

p = detection probability

z_i = true occupancy state at site i

ψ = occupancy probability

α_j = model parameters relating detection probability and detection covariates A_j

β_j = model parameters relating occupancy probability and occupancy covariates B_j

MODELING APPROACH



SPOCCUPANCY MODEL ANALYSIS

Occurrence (logit scale):

| | Mean | SD | 2.5% | 50% | 97.5% | Rhat | ESS |
|-------------|---------|--------|---------|---------|---------|---------|------|
| (Intercept) | 0.0109 | 1.6356 | -3.1908 | 0.0053 | 3.2795 | 1.0001 | 6261 |
| precip | 0.0080 | 1.6405 | -3.1507 | 0.0099 | 3.1966 | 1.0003 | 6000 |
| tmin | 0.0277 | 1.6488 | -3.2144 | 0.0509 | 3.3188 | 1.0002 | 6000 |
| tmax | -0.0076 | 1.6594 | -3.2778 | -0.0372 | 3.2979 | 1.0003 | 6000 |
| EVI | 0.0144 | 1.6522 | -3.2616 | 0.0334 | 3.2487 | 1.0001 | 6580 |
| umdha | 1.7232 | 0.4624 | 1.1325 | 1.7046 | 2.3602 | 47.1902 | 2 |
| umdfire | -1.9763 | 0.2963 | -2.5103 | -1.9171 | -1.5225 | 14.0234 | 3 |

Detection (logit scale):

| | Mean | SD | 2.5% | 50% | 97.5% | Rhat | ESS |
|-------------|---------|--------|---------|---------|---------|--------|------|
| (Intercept) | -2.7726 | 0.2205 | -3.2018 | -2.7711 | -2.3404 | 1.0008 | 5593 |
| doy | 0.0027 | 0.0006 | 0.0015 | 0.0027 | 0.0040 | 1.0010 | 5456 |
| tod | -0.0378 | 0.0142 | -0.0658 | -0.0376 | -0.0096 | 1.0016 | 5808 |
| n.obs | 0.0764 | 0.0250 | 0.0269 | 0.0763 | 0.1256 | 1.0016 | 6000 |
| effort | 0.4051 | 0.0369 | 0.3334 | 0.4050 | 0.4781 | 1.0005 | 5696 |

Spatial Covariance:

| | Mean | SD | 2.5% | 50% | 97.5% | Rhat | ESS |
|----------|-------|--------|--------|--------|--------|--------|------|
| sigma.sq | 0.997 | 3.4121 | 0.1793 | 0.5864 | 3.8768 | 1.2514 | 4414 |
| phi | 0.000 | 0.0000 | 0.0000 | 0.0000 | 0.0000 | 1.0064 | 4146 |

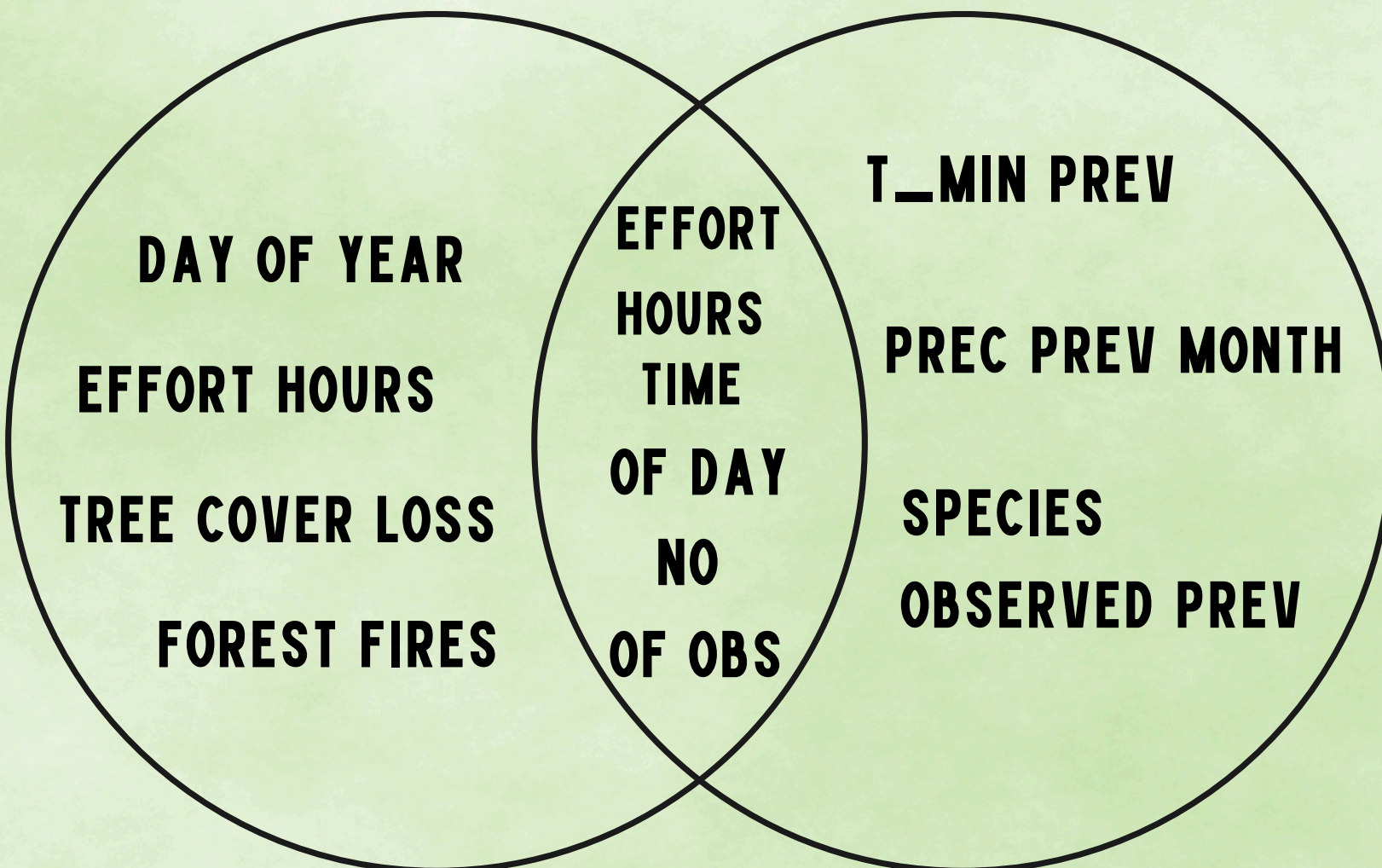
- Modelled with both spatial and temporal correlation effects
- Analysis shows that the detection covariates such as day of year, time of day, number of effort hours, and occupancy covariates such as tree cover loss, and forest fire loss are significant
- Spatial correlation between sites is very high
- Performed posterior predictive checks to compute Bayesian p-value, WAIC
- **Bayesian p-value = 0.7525**
- **WAIC = 2661.56**

RESULTS AND CONCLUSIONS



SPOCCUPANCY

LASSO REGULARIZATION



SIGNIFICANT COVARIATES

- Among the ML models, Binary Logistic Regression with SMOTE performed better than the others
- Among the occupancy models, SpOccupancy models tPGOcc and stPGOcc performed similarly well

Limitations

- Sites clustered in the same region -- low variance in occupancy covariates between sites.
- Variable and sometimes strong class imbalance
- Environmental data collected at different frequencies in time.

Future directions

- Model with more species across multiple sites in the Amazon rainforest
- Implement spatial correlation with ML models

**THANK
YOU!**

